

Data sheet for SIMOTICS S-1FK7



MLFB-Ordering data 1FK7061-4CF71-1RH0

Client order no. :
Order no. :
Offer no. :
Remarks :

Item no. :
Consignment no. :
Project :

Engineering data		Mechanical data	
Rated speed (100 K)	3000 rpm	Motor type	Permanent-magnet synchronous motor
Number of poles	6	Motor type	High Dynamic
Rated torque (100 K)	5.4 Nm	Shaft height	63
Rated current	5.3 A	Cooling	Natural cooling
Static torque (60 K)	5.30 Nm	Radial runout tolerance	0.040 mm
Static torque (100 K)	6.40 Nm	Concentricity tolerance	0.10 mm
Stall current (60 K)	4.95 A	Axial runout tolerance	0.10 mm
Stall current (100 K)	6.10 A	Vibration severity grade	Grade A
Moment of inertia	5.100 kgcm²	Connector size	1
Efficiency	93.0 %	Degree of protection	IP64
Physical constants		Design acc. to Code I	IM B5 (IM V1, IM V3)
Torque constant	1.05 Nm/A	Temperature monitoring	Pt1000 temperature sensor
Voltage constant at 20° C	67.5 V/1000*min ⁻¹	Electrical connectors	Connectors for signals and power rotatable
Winding resistance at 20° C	0.71 Ω	Color of the housing	Standard (Anthracite RAL 7016)
Rotating field inductance	22.0 mH	Holding brake	with holding brake
Electrical time constant	31.00 ms	Shaft end	Plain shaft
Mechanical time constant	0.79 ms	Encoder system	Encoder AM20DQI: absolute encoder 20 bits (resolution 1048576, encoder-internal 512 S/R) + 12 bits multi-turn (traversing range 4096 revolutions)
Thermal time constant	45 min		
Shaft torsional stiffness	26500 Nm/rad		
Net weight of the motor	11.0 kg		



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Optimum operating point		Recommended Motor Module	
Optimum speed	3000 rpm	Rated inverter current	9 A
Optimum power	1.7 kW	Maximum inverter current	27 A
Limiting data		Maximum torque	17.30 Nm
Max. permissible speed (mech.)	7500 rpm		
Max. permissible speed (inverter)	7500 rpm		
Maximum torque	17.3 Nm		
Maximum current	18.5 A		
Holding brake			
Holding brake version	Permanent-magnet brake		
Holding torque	13.0 Nm		
Power supply voltage	DC 24 V ± 10 %		
Coil current	0.8 A		
Opening time	100 ms		
Closing time	50 ms		
Highest braking work	380 J		